

# Global solvability of a quasilinear SPDE

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This talk is based on the joint work [2] with T. Funaki, Waseda University. Let  $g \in C^4(\mathbb{R})$  such that  $c_- \leq g'(v) \leq c_+$  holds for some  $c_-, c_+ > 0$  and  $a = g'$ . We mainly study the global-in-time solvability and establish the convergence of the solution to the stationary solution as  $t \rightarrow \infty$  for the following quasilinear stochastic partial differential equation (SPDE) defined in paracontrolled sense:

$$\partial_t u = a(\nabla u) \Delta u + g(\nabla u) \cdot \xi, \quad (1.1)$$

on one dimensional torus  $\mathbb{T} \simeq [0, 1)$  having the spatial noise  $\xi \in C^{\alpha-2}$ ,  $\alpha \in (\frac{13}{9}, \frac{3}{2})$ , where  $\nabla = \partial_x$ ,  $\Delta = \partial_x^2$  and  $C^\alpha \equiv C^\alpha(\mathbb{T})$  denotes the Hölder-Besov space on  $\mathbb{T}$  with regularity exponent  $\alpha \in \mathbb{R}$  equipped with the norm  $\|\cdot\|_{C^\alpha}$ . The SPDE (1.1) can be derived from a microscopic particle system in random environment on 1-d discrete lattice and the local-in-time solvability of (1.1) without restriction  $a = g'$  was recently studied in [1].

For our purpose, it turns out to be more convenient to study the SPDE in the form of

$$\partial_t v = \Delta\{\varphi(v)\} + \nabla\{\varphi(v)\xi\}, \quad (1.2)$$

on  $\mathbb{T}$ , where  $\varphi \in C^4(\mathbb{R})$  such that  $c_- \leq \varphi'(v) \leq c_+$  for some  $c_-, c_+ > 0$ . In fact, roughly speaking, we have  $v = \nabla u$  for  $\varphi = g$ . Note that (1.2) has a mass conservation law:

$$\int_{\mathbb{T}} v(t, x) dx = m \in \mathbb{R}. \quad (1.3)$$

To describe stationary solutions of (1.2), for a given  $\xi$ , we define its integral  $\eta(x) := \langle \xi, 1_{[0, x]} \rangle \equiv \int_0^x \xi(y) dy$ ,  $x \in \mathbb{T}$ . Note that  $\eta$  is not periodic, but  $\tilde{\eta}(x) := \langle \xi - \sigma, 1_{[0, x]} \rangle = \eta(x) - \sigma x$  is periodic, where

$$\sigma \equiv \sigma_\xi := \xi(\mathbb{T}) = \langle \xi, 1 \rangle = \eta(1) \in \mathbb{R}.$$

It is known that  $\eta \in C^{\alpha-1}(\mathbb{R})$ . Typically, we can take  $\xi = \dot{w}(x) + \sigma$  with a periodic Brownian motion  $w(x)$ ,  $x \in \mathbb{T}$  and  $\sigma \in \mathbb{R}$ . The most interesting noise is  $\xi = \dot{w}$  and, in this case,  $\sigma_\xi = 0$  holds.

Then, from  $\eta$ , we define a function  $\theta(x) = \theta_\xi(x)$  on  $\mathbb{T}$  and a constant  $\mu_\xi \in \mathbb{R}$ , respectively, by

$$\theta(x) \equiv \theta(x) := e^{-\eta(x)} \left\{ \mu \int_0^x e^{\eta(y)} dy + 1 \right\}, \quad x \in \mathbb{T},$$
$$\mu_\xi := \frac{e^{\eta(1)} - 1}{\int_0^1 e^{\eta(y)} dy}.$$

By the definition of  $\theta(x)$ , one has that  $\Delta(z\theta) + \nabla(z\theta \cdot \xi) = 0$  holds for every  $z \in \mathbb{R}$  at least if  $\xi \in C(\mathbb{T})$ . In particular,  $v = \varphi^{-1}(z\theta)$  are stationary solutions of (1.2), where  $\varphi^{-1}$  is the inverse function of  $\varphi$ .

For each conserved mass  $m \in \mathbb{R}$  given as in (1.3), determine  $z = z_m \in \mathbb{R}$  uniquely by the relation

$$m = \int_{\mathbb{T}} \varphi^{-1}(z\theta(x)) dx. \quad (1.4)$$

Since  $\varphi$  is strictly increasing, (1.4) determines a one to one relation between  $z$  and  $m$ . Then, one has that

$$\bar{v}_m(x) := \varphi^{-1}(z_m\theta(x))$$

is a stationary solution of (1.2) satisfying  $\int_{\mathbb{T}} v dx = m$  in distributional sense.

Let us now state the first main result.

**Theorem 1.1.** *For every initial value  $v_0 \in C^{\alpha-1}$ , the SPDE (1.2) has a global-in-time solution  $v(t) \in C^{\alpha-1}$  for all  $t \geq 0$ . Moreover, if  $|\mu_\xi|$  is sufficiently small,  $v(t)$  converges exponentially fast to  $\bar{v}_m$  in  $C^{\alpha-1}$  as  $t \rightarrow \infty$ :*

$$\|v(t) - \bar{v}_m\|_{C^{\alpha-1}} \leq Ce^{-ct},$$

for some  $c, C > 0$ , where  $m$  is determined from  $v_0$  as  $m = \int_{\mathbb{T}} v_0(x) dx$ .

This theorem for the slope  $v(t) = \nabla u(t)$  of  $u(t)$  implies the following result for  $u(t)$  itself.

**Theorem 1.2.** *The SPDE (1.1) has a global-in-time solution  $u(t) \in C^\alpha$  for all  $t \geq 0$ . Moreover, if  $|\mu_\xi|$  is sufficiently small as in Theorem 1.1,  $u(t)$  has the following uniform bound in  $t$ :*

$$\sup_{t \geq 0} \|u(t) - z_0 \mu_\xi t\|_{C^\alpha} < \infty,$$

where  $z_0$  is defined by (1.4) with  $m = 0$ . In particular, we have  $\frac{1}{t}u(t, x)$  converges uniformly on  $\mathbb{T}$  to  $z_0 \mu_\xi$  as  $t \rightarrow \infty$ .

## References

- [1] T. FUNAKI, M. HOSHINO, S. SETHURAMAN AND B. XIE, *Asymptotics of PDE in random environment by paracontrolled calculus*, Annales de l'Institut Henri Poincaré-Probabilités et Statistiques 57 (2021), No. 3, 1702–1735. doi.org/10.1214/20-AIHP1129.
- [2] T. FUNAKI AND B. XIE, *Global solvability and convergence to stationary solutions in singular quasilinear stochastic PDEs*, arXiv:2106.01102.