

**Stochastic complex
Ginzburg-Landau equation with
space-time white noise
(Joint work with Dr. Masato Hoshino and
Prof. Yuzuru Inahama)**

Nobuaki Naganuma

Graduate School of Engineering Science, Osaka University

Nov. 11, 2016

We prove local well-posedness of CGL

We prove local well-posedness of CGL

$$\begin{cases} \partial_t u = (i + \mu) \Delta u + \nu(1 - |u|^2)u + \xi, \\ u(0, \cdot) = u_0(\cdot), \end{cases} \quad \text{on } (0, \infty) \times \mathbf{T}^3,$$

where

- $\mathbf{T}^3 = (\mathbf{R}/\mathbf{Z})^3$: 3-dim. torus,
- ξ : $\mathbf{C}$ -val. space-time white noise,
- $i = \sqrt{-1}$,
- μ is a positive constant,
- ν is a complex constant.

We prove local well-posedness of CGL

We prove local well-posedness of CGL

$$\begin{cases} \partial_t u = (i + \mu) \Delta u + \nu(1 - |u|^2)u + \xi \\ \quad \quad \quad \text{on } (0, \infty) \times \mathbf{T}^3, \\ u(0, \cdot) = u_0(\cdot), \end{cases}$$

where

- $\mathbf{T}^3 = (\mathbf{R}/\mathbf{Z})^3$: 3-dim. torus,
- ξ : $\mathbf{C}$ -val. space-time white noise,

The white noise is too rough to define $|u|^2 u$.

Notation

- $\mathcal{D}$: the space of all smooth functions on $\mathbf{T}^3$,
- $\mathcal{D}'$: the dual of $\mathcal{D}$,
- $\{\mathbf{e}_k\}_{k \in \mathbf{Z}^3}$: CONS of $L^2(\mathbf{T}^3)$, i.e. $\mathbf{e}_k(x) = e^{2\pi i k \cdot x}$,
- $\{\rho_m\}_{m=-1}^\infty$: dyadic partition of unity,
 - (1) $\rho_m: \mathbf{R} \rightarrow [0, 1]$, radial, smooth,
 - (2) $\text{supp}(\rho_{-1}) \subset B(0, \frac{4}{3})$,
 $\text{supp}(\rho_0) \subset B(0, \frac{8}{3}) \setminus B(0, \frac{4}{3})$,
 - (3) $\rho_m(\cdot) = \rho_0(2^{-m}\cdot)$,
 - (4) $\sum_{m=-1}^\infty \rho_m(\cdot) = 1$,

Notation

- $\mathcal{F}f(k) = \hat{f}(k) = \int_{\mathbf{T}^3} \mathbf{e}_{-k}(x) f(x) dx$ for $k \in \mathbf{Z}^3$,
- $\mathcal{F}^{-1}\phi(x) = \sum_{k \in \mathbf{Z}^3} \phi(k) \mathbf{e}_k(x)$ for $x \in \mathbf{T}^3$
- $\phi(D)f = \mathcal{F}^{-1}\phi\mathcal{F}f = \sum_{k \in \mathbf{Z}^3} \phi(k) \hat{f}(k) \mathbf{e}_k$,
- $\Delta_m = \rho_m(D)$,
- $\mathcal{C}^\alpha$: the Besov-Hölder space with the Hölder exponent $\alpha \in \mathbf{R}$, i.e. the completion of $C^\infty(\mathbf{T}^3, \mathbf{C})$ under the norm

$$\|f\|_{\mathcal{C}^\alpha} = \sup_{m \geq -1} 2^{m\alpha} \|\Delta_m f\|_{L^\infty}$$

$\alpha + \beta > 0$ is necessary to define fg !

For every $f \in \mathcal{C}^\alpha$, $g \in \mathcal{C}^\beta$, a formal calc. implies

$$\begin{aligned} fg &= \left(\sum \Delta_{m_1} f \right) \left(\sum \Delta_{m_2} g \right) \\ &= \left(\sum_{m_1 \geq m_2 + 2} + \sum_{|m_1 - m_2| \leq 1} + \sum_{m_1 + 2 \leq m_2} \right) \Delta_{m_1} f \Delta_{m_2} g \\ &=: f \oslash g + f \odot g + f \otimes g \end{aligned}$$

$\alpha + \beta > 0$ is necessary to define fg !

Theorem (Bony '81)

(1) $\forall \alpha, \forall \beta, \|f \otimes g\|_{\mathcal{C}^{\alpha \wedge 0 + \beta}} \lesssim \|f\|_{\mathcal{C}^\alpha} \|g\|_{\mathcal{C}^\beta}.$

(2) *If $\alpha + \beta > 0$, then $\|f \odot g\|_{\mathcal{C}^{\alpha + \beta}} \lesssim \|f\|_{\mathcal{C}^\alpha} \|g\|_{\mathcal{C}^\beta}.$*

If and only if $\alpha + \beta > 0$, we can define

$$fg = \underbrace{f \otimes g}_{\mathcal{C}^{\beta \wedge 0 + \alpha}} + \underbrace{f \odot g}_{\mathcal{C}^{\alpha + \beta}} + \underbrace{f \otimes g}_{\mathcal{C}^{\alpha \wedge 0 + \beta}} \in \mathcal{C}^{\alpha \wedge \beta \wedge (\alpha + \beta)}.$$

Commutator estimate

Proposition

Let $0 < \alpha < 1$, $\beta, \gamma \in \mathbf{R}$ satisfy $\beta + \gamma < 0$ and $\alpha + \beta + \gamma > 0$. For $f, g, h \in C^\infty(\mathbf{T}^3, \mathbf{C})$, we set

$$R(f, g, h) = (f \otimes g) \odot h - f(g \odot h).$$

Then R is extended to a conti. trilinear map from $\mathcal{C}^\alpha \times \mathcal{C}^\beta \times \mathcal{C}^\gamma$ to $\mathcal{C}^{\alpha+\beta+\gamma}$ uniquely.

From this proposition, we obtain

$$\begin{aligned} fgh &= f(g \odot h) + (f \odot g)h + R(f, g, h) \\ &\quad + (f \otimes g)(\otimes + \otimes)h + (f \otimes g)h. \end{aligned}$$

Simplified Schauder estimate

- $\mathcal{L}^1 = \partial_t - \{(i + \mu)\Delta - 1\},$
- $P_t^1 = e^{t\{(i+\mu)\Delta-1\}}$ and $I(u)_t = \int_0^t P_{t-s}^1 u_s ds,$
- $C_T \mathcal{C}^\alpha = C([0, T], \mathcal{C}^\alpha)$ which is equipped with the supremum norm $\|\cdot\|_{C_T \mathcal{C}^\alpha}.$

Proposition

For every $u \in L_T^\infty \mathcal{C}^\alpha$ and $\gamma \in [\alpha, \alpha + 2)$, we have

$$\|I(u)\|_{C_T \mathcal{C}^\gamma} \lesssim T^{\frac{\alpha+2-\gamma}{2}} \|u\|_{L_T^\infty \mathcal{C}^\alpha}.$$

The white noise is too rough to define $|u|^2 u$

■ Note $\mathcal{L}^1 u = -\nu u^2 \bar{u} + (\nu + 1)u + \xi$.

■ Consider the linearized eq. $\mathcal{L}^1 Z = \xi$.

From $\xi \in L_T^\infty \mathcal{C}^{-\frac{5}{2}-}$ and the Schauder est., the sol. $Z = I(\xi)$ satisfies

$$Z \in C_T \mathcal{C}^{-\frac{1}{2}-}.$$

■ Since the irregularity of u comes from ξ , it is natural to guess

$$u \in C_T \mathcal{C}^{-\frac{1}{2}-}.$$

■ The product $|u_t|^2 u_t = u_t^2 \bar{u}_t$ is not defined.

Main result

- Let $\{\rho^\epsilon\}_{0 < \epsilon < 1}$ be a mollifier on $\mathbf{T}^3$,
- Set $\xi^\epsilon = \rho^\epsilon * \xi$ for every $0 < \epsilon < 1$,
- Take some const. $\mathfrak{c}^\epsilon$, which $\mathfrak{c}^\epsilon \rightarrow \infty$ as $\epsilon \downarrow 0$,
- $0 < \kappa < \kappa' \ll 1$

Theorem (Hoshino-Inahama-N.)

Let $u_0 \in \mathcal{C}^{-\frac{2}{3} + \kappa'}$. Consider the renormalized eq.

$$\begin{cases} \partial_t u^\epsilon = (i + \mu) \Delta u^\epsilon + \nu(1 - |u^\epsilon|^2)u^\epsilon \\ \quad \quad \quad + \nu \mathfrak{c}^\epsilon u^\epsilon + \xi^\epsilon, \\ u(0, \cdot) = u_0(\cdot). \end{cases}$$

Theorem (Hoshino-Inahama-N.)

There exist a unique proc. u^ϵ and a random time T_^ϵ s.t.*

- *u^ϵ solves the eq. on $[0, T_*^\epsilon) \times \mathbf{T}^3$,*
- *T_*^ϵ converges to some a.s. positive random time T_* in probability,*
- *u^ϵ converges to some proc. u defined on $[0, T_*) \times \mathbf{T}^3$ in the sense that $u^\epsilon \rightarrow u$ in probability in $C_t \mathcal{C}^{-\frac{3}{2}+\kappa'}$ for every $0 < t < T_*$. Furthermore, u is indep. of the choice of ξ^ϵ .*

1 Introduction

2 Deterministic part

3 Probabilistic part

Strategy

- We discuss our problem as deterministic one.
- We take deterministic $\xi \in C_T \mathcal{C}^{-\frac{5}{2}-}$ and fix it.
Note $Z = I(\xi) \in C_T \mathcal{C}^{-\frac{1}{2}-}$.
- We construct
 - the product $u^2 \bar{u}$ by focusing on the most rough term in nonlinear terms,
 - a solution map from $\mathcal{X}_T^\kappa$ to $\mathcal{D}_T^{\kappa, \kappa'}$.

Rule and Notation

- We use the rule that

$$f \in \mathcal{C}^\alpha, g \in \mathcal{C}^\beta \implies fg \in \mathcal{C}^{\alpha \wedge \beta \wedge (\alpha + \beta)}$$

for any $\alpha, \beta \in \mathbf{R}$.

- We use the tree-like symbols:

$$\dot{\mid} \rightsquigarrow Z = I(\xi), \quad \dot{\vdots} \rightsquigarrow \overline{Z}, \quad \ddot{\vee} \rightsquigarrow Z^2, \quad \dot{\vee} \rightsquigarrow Z\overline{Z}.$$

In this symbols,

dot $\rightsquigarrow$ the white noise,

line $\rightsquigarrow$ the operation I .

Reduction of our problem (Step 1)

Recall

$$\mathcal{L}^1 u = -\underbrace{\nu \underbrace{u^2 \bar{u}}_{-\frac{3}{2}-}}_{-\frac{3}{2}-} + (\nu + 1) \underbrace{u}_{-\frac{1}{2}-} + \underbrace{\xi}_{-\frac{5}{2}-}.$$

We set $u = u_1 + Z$ for $u_1 \in C_T \mathcal{C}^{\frac{1}{2}-}$ ($-\frac{3}{2} + 2 = \frac{1}{2}$).

Then

$$\mathcal{L}^1 u_1 = -\nu(u_1 + Z)^2(\bar{u}_1 + \bar{Z}) + (\nu + 1)(u_1 + Z).$$

Reduction of our problem (Step 2)

Note that the term $(u_1 + Z)^2(\overline{u}_1 + \overline{Z})$ is equal to

$$\underbrace{
 \underbrace{u_1^2 u_1}_{+\frac{1}{2}-} + \underbrace{u_1^2 \overline{Z}}_{0-} + 2 \underbrace{u_1 \overline{u}_1 Z}_{0-} + 2 \underbrace{u_1 \overbrace{Z \overline{Z}}^{-1-}}_{-1-} + \underbrace{\overline{u}_1 \underbrace{Z^2}_{-1-}}_{-1-} + \underbrace{Z^2 \overline{Z}}_{-\frac{3}{2}-}
 }_{-1-}$$

- We replace $Z\overline{Z}$, Z^2 and $Z^2\overline{Z}$ by $X \overset{\circ}{\mathbb{V}}, X \overset{\circ}{\mathbb{V}} \in C_T \mathcal{C}^{-1-}$ and $X \overset{\circ}{\mathbb{V}} \in C_T \mathcal{C}^{-\frac{3}{2}-}$, respectively, because they are ill-posed.
- We introduce $W \in C_T \mathcal{C}^{\frac{1}{2}-}$ s.t. $\mathcal{L}^1 W = X \overset{\circ}{\mathbb{V}}$ and set $u_1 = u_2 - \nu W$ for $u_2 \in C_T \mathcal{C}^{1-}$.

Then

$$\begin{aligned}
 (*) \quad \mathcal{L}^1 u_2 &= -\nu \{ (u_2 - \nu W)^2 (\overline{u_2} - \overline{\nu W}) + (u_2 - \nu W)^2 \overline{Z} \\
 &\quad + 2(u_2 - \nu W)(\overline{u_2} - \overline{\nu W})Z \\
 &\quad + 2(u_2 - \nu W)X^{\bullet\circ} + (\overline{u_2} - \overline{\nu W})X^{\bullet\bullet} \} \\
 &\quad + (\nu + 1)(u_2 - \nu W + Z) \\
 &= -\nu \{ 2(u_2 - \nu W)X^{\bullet\circ} + (\overline{u_2} - \overline{\nu W})X^{\bullet\bullet} \} + G_{-1}(u_2).
 \end{aligned}$$

In (RHS), the following terms are ill-defined:

$$\begin{aligned}
 &u_2 W \overline{Z}, \quad W^2 \overline{Z}, \quad u_2 \overline{W} Z, \quad \overline{u_2} W Z, \quad W \overline{W} Z, \\
 &u_2 X^{\bullet\circ}, \quad W X^{\bullet\circ}, \quad \overline{u_2} X^{\bullet\bullet}, \quad \overline{W} X^{\bullet\bullet}.
 \end{aligned}$$

Definitions of $W\bar{Z}$, $W^2\bar{Z}$, $\bar{W}Z$, WZ and $W\bar{W}Z$

- We introduce X , X  $\in C_T\mathcal{C}^{0-}$ and define $WZ, W\bar{Z}, W^2\bar{Z}, W\bar{W}Z \in C_T\mathcal{C}^{-\frac{1}{2}-}$.
- From $u_2 \in C_T\mathcal{C}^{1-}$, the products $u_2 W\bar{Z}$, $u_2 \bar{W}Z$ and $\bar{u}_2 WZ$ are well-defined.
- In fact

$$WZ = W(\oplus + \oplus)Z + X$$


$$W\bar{Z} = W(\oplus + \oplus)Z + X$$

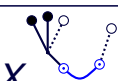

Definitions of $W\bar{Z}$, $W^2\bar{Z}$, $\bar{W}Z$, WZ and $W\bar{W}Z$

- From the commutator estimate, we can define

$$W^2\bar{Z} = W\bar{Z}W$$

$$= 2WX \text{  + R(W, \bar{Z}, W) \\ + (W \otimes \bar{Z})(\otimes + \otimes)W + W(W \otimes \bar{Z}),$$

$$W\bar{W}Z = \bar{W}ZW$$

$$= \bar{W}X \text{  + \overline{WX \text{ }} + R(\bar{W}, Z, W) \\ + (\bar{W} \otimes Z)(\otimes + \otimes)W + W(\bar{W} \otimes Z).$$

Definitions $WX^{\vee}$ and $\overline{WX}^{\vee}$

- We introduce $X^{\vee}$ , $X^{\vee}$  $\in C_T \mathcal{C}^{-1-}$ and define

$$\begin{aligned}
 WX^{\vee} &= W(\oplus + \oplus)X^{\vee} + X^{\vee} \text{  }, \\
 \overline{WX}^{\vee} &= \overline{WX^{\vee}} \\
 &= W(\oplus + \oplus)X^{\vee} + X^{\vee} \text{  }.
 \end{aligned}$$

We cannot define $u_2 X^{\circ}$ and $\overline{u_2} X^{\circ}$

- Since $u_2 \in C_T \mathcal{C}^{1-}$ and $X^{\circ}, X^{\circ} \in C_T \mathcal{C}^{-1-}$, we cannot define $u_2 X^{\circ}$ and $\overline{u_2} X^{\circ}$.
- The replacement $u_2 = u_3 + (\text{proc.})$ does not work well. Because $u_3 \in C_T \mathcal{C}^{1-}$.
- We need new idea.

Reduction of our problem (Step 3)

We consider the following system:

$$\mathcal{L}^1 v = F(v, w), \quad \mathcal{L}^1 w = G_0(v, w) + G_{-1}(v + w),$$

where

$$F(v, w) = -v\{2(v + w - vW) \otimes X^{\nabla} \\ + (\bar{v} + \bar{w} - \bar{v}\bar{W}) \otimes X^{\nabla}\},$$

$$G_0(v, w) = -v\{2(v + w - vW)(\otimes + \odot)X^{\nabla} \\ + (\bar{v} + \bar{w} - \bar{v}\bar{W})(\otimes + \odot)X^{\nabla}\}$$

Then $u_2 = v + w \in C_T \mathcal{C}^{1-}$ solves $(*)$.

Regularity of v and ill-posedness of $v \odot X^{\dot{V}}$

- $F(v, w) \in C_T \mathcal{C}^{-1-}$ follows from
 - $v + w \in C_T \mathcal{C}^{1-}$, $W \in C_T \mathcal{C}^{\frac{1}{2}-}$,
 - $X^{\dot{V}_\circ}, X^{\dot{V}} \in C_T \mathcal{C}^{-1-}$.
- Hence, $v \in C_T \mathcal{C}^{+1-}$.
- The resonants $v \odot X^{\dot{V}_\circ}$, $\bar{v} \odot X^{\dot{V}}$ are ill-posed.

Definition of $\nu \odot X^{\dot{V}}$ and $\bar{\nu} \odot X^{\dot{V}}$

- In order to define them, we introduce

- $X^{\text{Y-shape}} \in C_T \mathcal{C}^{+1-}$ s.t. $\mathcal{L}^1 X^{\text{Y-shape}} = X^{\dot{V}}$,

- $X^{\text{Y-shape}} \in C_T \mathcal{C}^{+1-}$ s.t. $\mathcal{L}^1 X^{\text{Y-shape}} = X^{\dot{V}}$,

- $X^{\text{cup-shape 1}}, X^{\text{cup-shape 2}}, X^{\text{cup-shape 3}}, X^{\text{cup-shape 4}} \in C_T \mathcal{C}^{0-}$.

- Define $\text{com}(\nu, w) \in C_T \mathcal{C}^{1+}$ by

$$\begin{aligned} \nu + \nu \{ 2(\nu + w - \nu W) \otimes X^{\text{Y-shape}} \\ + (\bar{\nu} + \bar{w} - \bar{\nu} \bar{W}) \otimes X^{\text{Y-shape}} \}. \end{aligned}$$

■ Note that

$$v = \text{com}(v, w) - v\{2(v + w - vW) \otimes X \begin{array}{c} \bullet \\ \vdots \\ \circ \end{array} + (\bar{v} + \bar{w} - \bar{v}\bar{W}) \otimes X \begin{array}{c} \bullet \quad \bullet \\ \vdots \quad \vdots \\ \circ \quad \circ \end{array} \}$$

and

$$\begin{aligned} & ((v + w - vW) \otimes X \begin{array}{c} \bullet \\ \vdots \\ \circ \end{array}) \odot X \begin{array}{c} \bullet \\ \vdots \\ \circ \end{array} \\ &= R((v + w - vW), X \begin{array}{c} \bullet \\ \vdots \\ \circ \end{array}, X \begin{array}{c} \bullet \\ \vdots \\ \circ \end{array}) \\ &+ (v + w - vW)(X \begin{array}{c} \bullet \\ \vdots \\ \circ \end{array} \odot X \begin{array}{c} \bullet \\ \vdots \\ \circ \end{array}). \end{aligned}$$

■ $v \odot X^{\vee}$ is defined by

$$\begin{aligned}
 & - \gamma \{ 2(v + w - \gamma W) X^{\vee} \\
 & \quad + (\bar{v} + \bar{w} - \bar{\gamma} \bar{W}) X^{\vee} \\
 & \quad + 2R(v + w - \gamma W, X^{\vee}, X^{\vee}) \\
 & \quad + R(\bar{v} + \bar{w} - \bar{\gamma} \bar{W}, X^{\vee}, X^{\vee}) \} \\
 & \quad + \text{com}(v, w) \odot X^{\vee}.
 \end{aligned}$$

■ $\bar{v} \odot X^{\vee}$ is defined in the similar way.

We can construct a conti. sol. map

For every $0 < \kappa < \kappa' < 1/18$ and $T > 0$, we set

$$\mathcal{X}_T^\kappa = \mathcal{C}_T \mathcal{C}^{-\frac{1}{2}-\kappa} \times \dots \ni X = (X^1, \dots),$$
$$\mathcal{D}_T^{\kappa, \kappa'} \subset \mathcal{C}_T \mathcal{C}^{-\frac{2}{3}+\kappa'} \times \mathcal{C}_T \mathcal{C}^{-\frac{1}{2}-2\kappa}.$$

We call $X \in \mathcal{X}_T^\kappa$ driving vector.

Theorem

- (1) For every $(v_0, w_0) \in \mathcal{C}^{-\frac{2}{3}+\kappa'} \times \mathcal{C}^{-\frac{1}{2}-2\kappa}$ and $X \in \mathcal{X}_T^\kappa$, there exists $T_* \in (0, 1]$ such that the system admits a unique sol. $(v, w) \in \mathcal{D}_{T_*}^{\kappa, \kappa'}$.
- (2) The map $(v_0, w_0, X) \mapsto (v, w)$ is conti.

1 Introduction

2 Deterministic part

3 Probabilistic part

Construction of a driving vector X

We construct a driving vector $X = (X^\bullet, \dots)$ s.t.

$$X^\bullet = I(\xi),$$

where $I(u) = P_t^1 \int_{-\infty}^0 P_{-s}^1 u_s ds + \int_0^t P_{t-s}^1 u_s ds$.

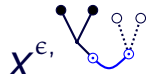
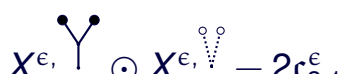
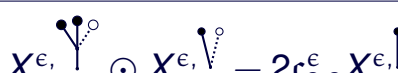
To this end, we set

- $\chi^\epsilon = \hat{\rho}^\epsilon,$
- $\xi_t^\epsilon = \rho^\epsilon * \xi_t,$
- $X^{\epsilon,\bullet} = Z^\epsilon = I(\xi^\epsilon),$
- $c_1^\epsilon = \mathbf{E}[Z_{(t,x)}^\epsilon \overline{Z_{(t,x)}^\epsilon}]:$ const. indep. of $(t, x).$

We define distributions $X^{\epsilon, \tau}$ as follows:

Symbol	Definition
$X^{\epsilon, \overset{\bullet}{ }}$	Z^{ϵ}
$X^{\epsilon, \overset{\circ}{ }}$	$\overline{X^{\epsilon, \overset{\bullet}{ }}}$
$X^{\epsilon, \overset{\bullet}{V}}$	$(X^{\epsilon, \overset{\bullet}{ }})^2$
$X^{\epsilon, \overset{\bullet}{V} \overset{\circ}{ }}$	$X^{\epsilon, \overset{\bullet}{ }} X^{\epsilon, \overset{\circ}{ }} - c_1^{\epsilon}$
$X^{\epsilon, \overset{\circ}{V}}$	$(X^{\epsilon, \overset{\circ}{ }})^2$
$X^{\epsilon, \overset{\bullet}{V} \overset{\circ}{V}}$	$X^{\epsilon, \overset{\bullet}{V}} X^{\epsilon, \overset{\circ}{ }} - 2c_1^{\epsilon} X^{\epsilon, \overset{\bullet}{ }}$

Symbol	Definition
	$I(X^\epsilon, V)$
	$I(X^\epsilon, V^\circ)$
$X^\epsilon, \text{Y-junction with two solid black inputs and one open input} = W^\epsilon$	$I(X^\epsilon, V^\circ)$
	$X^\epsilon, \text{Y-junction with two solid black inputs and one open input} \odot X^\epsilon, \text{Y-junction with two open inputs and one solid black output}$
	$X^\epsilon, \text{Y-junction with two solid black inputs and one open input} \odot X^\epsilon, \text{Y-junction with two open inputs and one open output}$

$$c_{2,1}^\epsilon = \frac{1}{2} \mathbf{E}[X_{(t,x)}^\epsilon \odot X_{(t,x)}^\epsilon], \quad c_{2,2}^\epsilon = \mathbf{E}[X_{(t,x)}^\epsilon \odot X_{(t,x)}^\epsilon].$$

Renormalized equation

For $X^\epsilon = (X^{\epsilon,1}, \dots)$, we consider the system

$$\begin{cases} \mathcal{L}^1 v^\epsilon = F(v^\epsilon, w^\epsilon), \\ \mathcal{L}^1 w^\epsilon = G_0(v^\epsilon, w^\epsilon) + G_{-1}(v^\epsilon + w^\epsilon). \end{cases}$$

Then, $u^\epsilon = Z^\epsilon - \nu W^\epsilon + v^\epsilon + w^\epsilon$ solves

$$\partial_t u^\epsilon = (i + \mu) \Delta u^\epsilon + \nu(1 - |u^\epsilon|^2)u^\epsilon + \nu c^\epsilon u^\epsilon + \xi^\epsilon.$$

with the initial condition $u_0^\epsilon = Z_0^\epsilon - \nu W_0^\epsilon + v_0^\epsilon + w_0^\epsilon$.

Here $c^\epsilon = 2(c_1^\epsilon - \overline{\nu c_{2,1}^\epsilon} - 2\nu c_{2,2}^\epsilon)$.

Convergence of X^ϵ

Let $\kappa > 0$, $T > 0$ and $1 < p < \infty$.

Proposition

$$\lim_{\epsilon \downarrow 0} \mathbf{E}[\|X^{\cdot,1} - X^{\epsilon,\cdot,1}\|_{C_T \mathcal{C}^{-1/2-\kappa}}^p] = 0.$$

Proposition

For $\tau = \begin{array}{c} \bullet \bullet \\ \diagdown \diagup \\ \circ \end{array}, \begin{array}{c} \bullet \circ \\ \diagdown \diagup \\ \circ \end{array}, \begin{array}{c} \bullet \bullet \\ | \quad | \\ \circ \end{array}, \begin{array}{c} \bullet \circ \\ | \quad | \\ \circ \end{array}, \begin{array}{c} \bullet \bullet \circ \\ | \quad | \quad | \\ \circ \end{array}, \begin{array}{c} \bullet \bullet \circ \\ \diagdown \quad \diagup \\ \circ \end{array}, \begin{array}{c} \bullet \bullet \circ \\ \diagdown \quad \diagup \\ \circ \end{array}, \begin{array}{c} \bullet \bullet \circ \\ \diagdown \quad \diagup \\ \circ \end{array},$
 $\begin{array}{c} \bullet \circ \quad \bullet \circ \\ \diagdown \quad \diagup \\ \circ \end{array}, \begin{array}{c} \bullet \circ \quad \bullet \circ \quad \bullet \circ \\ \diagdown \quad \diagup \\ \circ \end{array}, \begin{array}{c} \bullet \circ \quad \bullet \circ \quad \bullet \circ \\ \diagdown \quad \diagup \\ \circ \end{array}, \begin{array}{c} \bullet \circ \quad \bullet \circ \quad \bullet \circ \\ \diagdown \quad \diagup \\ \circ \end{array}, \{X^{\epsilon,\tau}\}_{0 < \epsilon < 1}$ is a Cauchy sequence in $L^p(\Omega, C_T \mathcal{C}^{\alpha^\tau - \kappa})$. Here, α^τ is suitable regularity.

From these propositions, we see the following:

Theorem

$\exists \mathcal{X}_T^{\kappa}$ -val process X s.t. $X^{\bullet} = I(\xi)$ and

$$\lim_{\epsilon \downarrow 0} \mathbf{E}[\|X - X^{\epsilon}\|_{\mathcal{X}_T^{\kappa}}^p] = 0.$$

Proof of $Z^\epsilon = X^{\epsilon, \circ} \rightarrow X^\circ = Z$

Proposition

For any $k \in \mathbf{Z}^3$ and $t \in \mathbf{R}$, $\hat{Z}_t(k)$ is a mean-zero $\mathbf{C}$ -val. Gaussian r.v. with covariance given by

$$\mathbf{E}[\hat{Z}_s(k) \overline{\hat{Z}_t(l)}] = \delta_{kl} \cdot \frac{e^{-4\pi^2 |k|^2 (s-t) - (4\pi^2 \mu |k|^2 + 1) |s-t|}}{4\pi^2 \mu |k|^2 + 1},$$
$$\mathbf{E}[\hat{Z}_s(k) \hat{Z}_t(l)] = 0 = \mathbf{E}[\hat{Z}_s(k) \hat{Z}_t(l)].$$

Proof of $Z^\epsilon = X^{\epsilon, \mathring{I}} \rightarrow X^{\mathring{I}} = Z$

Since $\hat{Z}_t^\epsilon = \chi^\epsilon(k) \hat{Z}_t$, we have

$$[\Delta_m(Z_t - Z_t^\epsilon)](x) = \sum_{k \in \mathbf{Z}^3} \rho_m(k) \{1 - \chi^\epsilon(k)\} \hat{Z}_t(k) \mathbf{e}_k(x).$$

Let $0 < h < \kappa < 1$. We obtain

$$\begin{aligned} \mathbf{E}[|\Delta_m(Z_t - Z_t^\epsilon)(x)|^2] &= \sum_{k \in \mathbf{Z}^3} \rho_m(k)^2 \{1 - \chi^\epsilon(k)\}^2 \mathbf{E}[|\mathbf{e}_k(x)|^2] \\ &\lesssim \sum_{k \in \mathbf{Z}^3} \rho_m(k)^2 (\epsilon |k|)^{2h} (|k|^2 + 1)^{-1} \\ &\lesssim \epsilon^{2h} (2^m)^{1+2h}. \end{aligned}$$

Proof of $Z^\epsilon = X^{\epsilon, \dot{I}} \rightarrow X^{\dot{I}} = Z$

Hence, for $\alpha = -1/2 - \kappa$, we have

$$\begin{aligned} \mathbf{E}[\|Z_t - Z_t^\epsilon\|_{\mathcal{C}^\alpha}^{2p}] &\lesssim \sum_{m=-1}^{\infty} 2^{(2\alpha p+1)m} \{\epsilon^{2h} (2^m)^{1+2h}\}^p \\ &= \epsilon^{2hp} \sum_{m=-1}^{\infty} 2^{(1-2(\kappa-h)p)m} \\ &\rightarrow 0. \end{aligned}$$

Proof of convergence of $X^{\epsilon, \overset{\circ}{V}}, X^{\epsilon, \overset{\circ}{V}}, \dots$

We calculate integrability of the kernels of the Itô-Wiener integral $X^{\epsilon, \tau}$. To this end, we use

- the product formula for the Itô-Wiener integral,
- the Fourier transform wrt time parameters of the kernels

Thank you for your attention.